

III Year - II Semester

L	T	P	C
4	0	0	3

## MICROPROCESSORS AND MICROCONTROLLERS

### UNIT-I:

**8086 ARCHITECTURE:** Main features, pin diagram/description, 8086 microprocessor family, 8086 internal architecture, bus interfacing unit, execution unit, interrupts and interrupt responses, 8086 system timing, minimum mode and maximum mode configuration.

### UNIT-II:

**8086 PROGRAMMING:** Program development steps, instructions, addressing modes, assembler directives, writing simple programs with an assembler, assembly language program development tools.

### UNIT-III:

**8086 INTERFACING :** Semiconductor memories interfacing (RAM,ROM), 8254 software programmable timer/counter, Intel 8259 programmable interrupt controller, software and hardware interrupt applications, Intel 8237a DMA controller, Intel 8255 programmable peripheral interface, keyboard interfacing, alphanumeric displays (LED,7-segment display, multiplexed 7-segment display, LCD), Intel 8279 programmable keyboard/display controller, stepper motor, A/D and D/A converters.

### UNIT-IV:

**80386 AND 80486 MICROPROCESSORS:** Introduction, programming concepts, special purpose registers, memory organization, moving to protected mode, virtual mode, memory paging mechanism, architectural differences between 80386 and 80486 microprocessors.

### UNIT-V:

**Intel 8051 MICROCONTROLLER:** Architecture, hardware concepts, input/output ports and circuits, external memory, counters/timers, serial data input/output, interrupts.

Assembly language programming: Instructions, addressing modes, simple programs.

Interfacing: keyboard, displays (LED, 7-segment display unit), A/D and D/A converters.

### UNIT-VI:

**PIC MICROCONTROLLER:** Introduction, characteristics of PIC microcontroller, PIC microcontroller families, memory organization, parallel and serial input and output, timers, Interrupts, PIC 16F877 architecture, instruction set of the PIC 16F877.

### Text Books:

1. Microprocessors and Interfacing – Programming and Hardware by Douglas V Hall, SSSP Rao, Tata McGraw Hill Education Private Limited, 3<sup>rd</sup> Edition.
2. The 8051 Microcontroller & Embedded Systems Using Assembly and C by Kenneth J.Ayala, Dhananjay V.Gadre,Cengage Learning , India Edition.

### References:

1. The Intel Microprocessors-Architecture, Programming, and Interfacing by Barry B.Brey, Pearson, Eighth Edition-2012.
2. Microprocessors and Microcontrollers-Architecture, Programming and System Design by Krishna Kant, PHI Learning Private Limited, Second Edition, 2014.
3. Microprocessors and Microcontrollers by N.Senthil Kumar, M.Saravanan and S.Jeevananthan, Oxford University Press, Seventh Impression 2013

III Year - II Semester

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>4</b>	<b>0</b>	<b>0</b>	<b>3</b>

## MICROWAVE ENGINEERING

### OBJECTIVES

The student will

- Understand fundamental characteristics of waveguides and Microstrip lines through electromagnetic field analysis.
- Understand the basic properties of waveguide components and Ferrite materials composition
- Understand the function, design, and integration of the major microwave components oscillators, power amplifier.
- Understand a Microwave test bench setup for measurements.

### UNIT I

**MICROWAVE TRANSMISSION LINES:** Introduction, Microwave Spectrum and Bands, Applications of Microwaves. Rectangular Waveguides – TE/TM mode analysis, Expressions for Fields, Characteristic Equation and Cut-off Frequencies, Filter Characteristics, Dominant and Degenerate Modes, Sketches of TE and TM mode fields in the cross-section, Mode Characteristics – Phase and Group Velocities, Wavelengths and Impedance Relations; Power Transmission and Power Losses in Rectangular Guide, Impossibility of TEM mode. Related Problems.

### UNIT II

**CIRCULAR WAVEGUIDES:** Introduction, Nature of Fields, Characteristic Equation, Dominant and Degenerate Modes.

Cavity Resonators– Introduction, Rectangular and Cylindrical Cavities, Dominant Modes and Resonant Frequencies, Q factor and Coupling Coefficients, Excitation techniques- waveguides and cavities, Related Problems.

**MICROSTRIP LINES**– Introduction, Zo Relations, Effective Dielectric Constant, Losses, Q factor.

### UNIT III

**MICROWAVE TUBES** :Limitations and Losses of conventional tubes at microwave frequencies. Re-entrant Cavities, Microwave tubes – O type and M type classifications. O-type tubes :2 Cavity Klystrons – Structure, Velocity Modulation Process and Applegate Diagram, Bunching Process and Small Signal Theory –Expressions for o/p Power and Efficiency, Applications, Reflex Klystrons – Structure, Applegate Diagram and Principle of working, Mathematical Theory of Bunching, Power Output, Efficiency, Electronic Admittance; Oscillating Modes and o/p Characteristics, Electronic and Mechanical Tuning, Applications, Related Problems.

### UNIT - IV

**HELIX TWTS:** Significance, Types and Characteristics of Slow Wave Structures; Structure of TWT and Suppression of Oscillations, Nature of the four Propagation Constants(Qualitative treatment).

#### M-type Tubes

Introduction, Cross-field effects, Magnetrons – Different Types, 8-Cavity Cylindrical Travelling Wave Magnetron – Hull Cut-off Condition, Modes of Resonance and PI-Mode Operation, Separation of PI-Mode, o/p characteristics.

## UNIT V

**WAVEGUIDE COMPONENTS AND APPLICATIONS - I** :Coupling Mechanisms – Probe, Loop, Aperture types. Waveguide Discontinuities – Waveguide irises, Tuning Screws and Posts, Matched Loads. Waveguide Attenuators – Resistive Card, Rotary Vane types; Waveguide Phase Shifters – Dielectric, Rotary Vane types. Scattering Matrix– Significance, Formulation and Properties. S-Matrix Calculations for – 2 port Junction, E-plane and H-plane Tees, Magic Tee, Hybrid Ring; Directional Couplers – 2Hole, Bethe Hole types, Ferrite Components– Faraday Rotation, S-Matrix Calculations for Gyrator, Isolator, Circulator, Related Problems.

## UNIT VI

**MICROWAVE SOLID STATE DEVICES:** Introduction, Classification, Applications. TEDs – Introduction, Gunn Diode – Principle, RWH Theory, Characteristics, Basic Modes of Operation, Oscillation Modes. Avalanche Transit Time Devices – Introduction, IMPATT and TRAPATT Diodes – Principle of Operation and Characteristics. **MICROWAVE MEASUREMENTS:** Description of Microwave Bench – Different Blocks and their Features, Precautions; Microwave Power Measurement – Bolometer Method. Measurement of Attenuation, Frequency, Q-factor, Phase shift, VSWR, Impedance Measurement.

### TEXT BOOKS:

1. Microwave Devices and Circuits – Samuel Y. Liao, PHI, 3rd Edition, 1994.
2. Foundations for Microwave Engineering – R.E. Collin, IEEE Press, John Wiley, 2nd Edition, 2002.

### REFERENCES:

1. Microwave Principles – Herbert J. Reich, J.G. Skalnik, P.F. Ordung and H.L. Krauss, CBS Publishers and Distributors, New Delhi, 2004
2. Microwave Engineering- Annapurna Das and Sisir K.Das, Mc Graw Hill Education, 3<sup>rd</sup> Edition.
3. Microwave and Radar Engineering-M.Kulkarni, Umesh Publications, 3<sup>rd</sup> Edition.
4. Microwave Engineering – G S N Raju , I K International
5. Microwave and Radar Engineering – G Sasibhushana Rao Pearson

**OUTCOMES** : After going through this course the student will be able to

- Design different modes in waveguide structures
- Calculate S-matrix for various waveguide components and splitting the microwave energy in a desired direction
- Distinguish between Microwave tubes and Solid State Devices, calculation of efficiency of devices.
- Measure various microwave parameters using a Microwave test bench

III Year - II Semester

L	T	P	C
4	0	0	3

## VLSI DESIGN

### Objectives:

#### The main objectives of this course are:

- Basic characteristics of MOS transistor and examines various possibilities for configuring inverter circuits and aspects of latch-up are considered.
- Design processes are aided by simple concepts such as stick and symbolic diagrams but the key element is a set of design rules, which are explained clearly.
- Basic circuit concepts are introduced for MOS processes we can set out approximate circuit parameters which greatly ease the design process.

### Outcomes:

#### At the end of this course the student can able to:

- Understand the properties of MOS active devices and simple circuits configured when using them and the reason for such encumbrances as ratio rules by which circuits can be interconnected in silicon.
- Know three sets of design rules with which nMOS and CMOS designs may be fabricated.
- Understand the scaling factors determining the characteristics and performance of MOS circuits in silicon.

### Syllabus:

#### UNIT-I:

**Introduction and Basic Electrical Properties of MOS Circuits:** Introduction to IC technology, Fabrication process: nMOS, pMOS and CMOS.  $I_{ds}$  versus  $V_{ds}$  Relationships, Aspects of MOS transistor Threshold Voltage, MOS transistor Trans, Output Conductance and Figure of Merit. nMOS Inverter, Pull-up to Pull-down Ratio for nMOS inverter driven by another nMOS inverter, and through one or more pass transistors. Alternative forms of pull-up, The CMOS Inverter, Latch-up in CMOS circuits, Bi-CMOS Inverter, Comparison between CMOS and BiCMOS technology.

(Text Book-1)

#### UNIT-II:

**MOS and Bi-CMOS Circuit Design Processes:** MOS Layers, Stick Diagrams, Design Rules and Layout, General observations on the Design rules, 2 $\mu$ m Double Metal, Double Poly, CMOS/BiCMOS rules, 1.2 $\mu$ m Double Metal, Double Poly CMOS rules, Layout Diagrams of NAND and NOR gates and CMOS inverter, Symbolic Diagrams-Translation to Mask Form.

(Text Book-1)

#### UNIT-III:

**Basic Circuit Concepts:** Sheet Resistance, Sheet Resistance concept applied to MOS transistors and Inverters, Area Capacitance of Layers, Standard unit of capacitance, Some area Capacitance Calculations, The Delay Unit, Inverter Delays, Driving large capacitive loads, Propagation Delays, Wiring Capacitances, Choice of layers.

**Scaling of MOS Circuits:** Scaling models and scaling factors, Scaling factors for device parameters, Limitations of scaling, Limits due to sub threshold currents, Limits on logic levels and supply voltage due to noise and current density. Switch logic, Gate logic.

(Text Book-1)

#### **UNIT-IV:**

**Chip Input and Output circuits:** ESD Protection, Input Circuits, Output Circuits and L(di/dt) Noise, On-Chip clock Generation and Distribution.

**Design for Testability:** Fault types and Models, Controllability and Observability, Ad Hoc Testable Design Techniques, Scan Based Techniques and Built-In Self Test techniques.

**(Text Book-2)**

#### **UNIT-V:**

**FPGA Design:** FPGA design flow, Basic FPGA architecture, FPGA Technologies, FPGA families- Altera Flex 8000FPGA, Altera Flex 10FPGA, Xilinx XC4000 series FPGA, Xilinx Spartan XL FPGA, Xilinx Spartan II FPGAs, Xilinx Vertex FPGA. Case studies: FPGA Implementation of Half adder and full adder.

**Introduction to synthesis:** Logic synthesis, RTL synthesis, High level Synthesis.

**(Reference Text Book-1)**

#### **UNIT-VI:**

**Introduction to Low Power VLSI Design:** Introduction to Deep submicron digital IC design, Low Power CMOS Logic Circuits: Over view of power consumption, Low –power design through voltage scaling, Estimation and optimisation of switching activity, Reduction of switching capacitance. Interconnect Design, Power Grid and Clock Design.

**(Text Book-2)**

#### **Text Books:**

1. Essentials of VLSI Circuits and Systems - Kamran Eshraghian, Douglas and A. Pucknell and Sholeh Eshraghian, Prentice-Hall of India Private Limited, 2005 Edition.
2. CMOS Digital Integrated Circuits Analysis and Design- Sung-Mo Kang, Yusuf Leblebici, Tata McGraw-Hill Education, 2003.

#### **References:**

1. Advanced Digital Design with the Verilog HDL, Michael D.Ciletti, Xilinx Design Series, Pearson Education
2. Analysis and Design of Digital Integrated Circuits in Deep submicron Technology, 3<sup>rd</sup> edition, David Hodges.

III Year - II Semester

L	T	P	C
4	0	0	3

## DIGITAL SIGNAL PROCESSING

### OBJECTIVES

The student will be able to

- Analyze the Discrete Time Signals and Systems
- Know the importance of FFT algorithm for computation of Discrete Fourier Transform
- Understand the various implementations of digital filter structures
- Learn the FIR and IIR Filter design procedures
- Know the need of Multirate Processing
- Learn the concepts of DSP Processors

**UNIT I INTRODUCTION:** Introduction to Digital Signal Processing: Discrete time signals & sequences, Classification of Discrete time systems, stability of LTI systems, Invertability, Response of LTI systems to arbitrary inputs. Solution of Linear constant coefficient difference equations. Frequency domain representation of discrete time signals and systems. Review of Z-transforms, solution of difference equations using Z-transforms, System function.

**UNIT II DISCRETE FOURIER SERIES & FOURIER TRANSFORMS:** Properties of discrete Fourier series, DFS representation of periodic sequences, Discrete Fourier transforms: Properties of DFT, linear filtering methods based on DFT, Fast Fourier transforms (FFT) - Radix-2 decimation in time and decimation in frequency FFT Algorithms, Inverse FFT.

**UNIT III. DESIGN OF IIR DIGITAL FILTERS& REALIZATIONS:** Analog filter approximations – Butter worth and Chebyshev, Design of IIR Digital filters from analog filters, Design Examples, Analog and Digital frequency transformations. Basic structures of IIR systems, Transposed forms.

### UNIT IV DESIGN OF FIR DIGITAL FILTERS & REALIZATIONS:

Characteristics of FIR Digital Filters, frequency response. Design of FIR Digital Filters using Window Techniques and Frequency Sampling technique, Comparison of IIR & FIR filters.

Basic structures of FIR systems, *Lattice structures, Lattice-ladder structures*

**UNIT V MULTIRATE DIGITAL SIGNAL PROCESSING:** Introduction, Decimation, Interpolation Sampling rate conversion, Implementation of sampling rate converters, *Applications – Sub-band Coding of Speech Signals, Implementation of Digital Filter Banks, Trans-multiplexers.*

**UNIT VI INTRODUCTION TO DSP PROCESSORS:** Introduction to programmable DSPs: Multiplier and Multiplier Accumulator, Modified bus structures and memory access schemes in P-DSPs, Multiple Access Memory, Multiported memory, VLIW architecture, Pipelining, Special addressing modes, On-Chip Peripherals. Architecture of TMS320C5X: Introduction, Bus Structure, Central Arithmetic Logic Unit, Auxiliary Register ALU, Index Register, Block Move Address Register, Parallel Logic Unit, Memory mapped registers, program controller, some flags in the status registers, On-chip memory, On-chip peripherals.

**TEXT BOOKS:**

1. Digital Signal Processing, Principles, Algorithms, and Applications: John G. Proakis, Dimitris G.Manolakis,Pearson Education / PHI, 2007.
2. Discrete Time Signal Processing – A.V.Oppenheim and R.W. Schaffer, PHI
3. Digital Signal Processors – Architecture, Programming and Applications,, B.Venkataramani, M.Bhaskar, TATA McGraw Hill, 2002
4. Digital Signal Processing – K Raja Rajeswari, I.K. International Publishing House

**Reference Books:**

1. Digital Signal Processing: Andreas Antoniou, TATA McGraw Hill , 2006
2. Digital Signal Processing: MH Hayes, Schaum's Outlines, TATA Mc-Graw Hill, 2007.
3. DSP Primer - C. Britton Rorabaugh, Tata McGraw Hill, 2005.
4. Fundamentals of Digital Signal Processing using Matlab – Robert J. Schilling, Sandra L. Harris,Thomson, 2007.
5. Digital Signal Processing – Alan V. Oppenheim, Ronald W. Schafer, PHI Ed., 2006
6. Digital Signal Processing – Ramesh babu, Sci Tech publications

**OUTCOMES**

After going through this course the student will be able to

- Apply the difference equations concept in the anayziation of Discrete time systems
- Use the FFT algorithm for solving the DFT of a given signal
- Design a Digital filter (FIR&IIR) from the given specifications
- Realize the FIR and IIR structures from the designed digital filter.
- Use the Multirate Processing concepts in various applications(eg: Design of phase shifters, Interfacing of digital systems...)
- Apply the signal processing concepts on DSP Processor.

III Year - II Semester

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>4</b>	<b>0</b>	<b>0</b>	<b>3</b>

**OOPS THROUGH JAVA  
OPEN ELECTIVE**

**OBJECTIVES:**

- Understanding the OOP's concepts, classes and objects, threads, files, applets, swings and act.
- This course introduces computer programming using the JAVA programming language with object-oriented programming principles.
- Emphasis is placed on event-driven programming methods, including creating and manipulating objects, classes, and using Java for network level programming and middleware development

**UNIT-I:**

Introduction to OOP, procedural programming language and object oriented language, principles of OOP, applications of OOP, history of java, java features, JVM, program structure.

Variables, primitive data types, identifiers, literals, operators, expressions, precedence rules and associativity, primitive type conversion and casting, flow of control.

**UNIT-II:**

Classes and objects, class declaration, creating objects, methods, constructors and constructor overloading, garbage collector, importance of static keyword and examples, this keyword, arrays, command line arguments, nested classes.

**UNIT-III:**

Inheritance, types of inheritance, super keyword, final keyword, overriding and abstract class.

Interfaces, creating the packages, using packages, importance of CLASSPATH and java.lang package. Exception handling, importance of try, catch, throw, throws and finally block, user-defined exceptions, Assertions.

**UNIT-IV:**

Multithreading: introduction, thread life cycle, creation of threads, thread priorities, thread synchronization, communication between threads. Reading data from files and writing data to files, random access file,

**UNIT-V:**

Applet class, Applet structure, Applet life cycle, sample Applet programs. Event handling: event delegation model, sources of event, Event Listeners, adapter classes, inner classes.

**UNIT-VI:**

AWT: introduction, components and containers, Button, Label, Checkbox, Radio Buttons, List Boxes, Choice Boxes, Container class, Layouts, Menu and Scrollbar.

**OUTCOMES:**

- Understand Java programming concepts and utilize Java Graphical User Interface in Program writing.
- Write, compile, execute and troubleshoot Java programming for networking concepts.
- Build Java Application for distributed environment.
- Design and Develop multi-tier applications.



- Identify and Analyze Enterprise applications.

**TEXT BOOKS:**

1. The complete Reference Java, 8<sup>th</sup> edition, Herbert Schildt, TMH.
2. Programming in JAVA, Sachin Malhotra, Saurabh Choudary, Oxford.
3. Introduction to java programming, 7<sup>th</sup> edition by Y Daniel Liang, Pearson.

**REFERENCE BOOKS:**

1. Swing: Introduction, JFrame, JApplet, JPanel, Componets in Swings, Layout Managers in
2. Swings, JList and JScrollPane, Split Pane, JTabbedPane, JTree, JTable, Dialog Box.

## **DATA MINING OPEN ELECTIVE**

### **OBJECTIVES:**

- Students will be enabled to understand and implement classical models and algorithms in data warehousing and data mining.
- They will learn how to analyze the data, identify the problems, and choose the relevant models and algorithms to apply.
- They will further be able to assess the strengths and weaknesses of various methods and algorithms and to analyze their behavior.

### **UNIT –I**

**Introduction:** Why Data Mining? What Is Data Mining? 1.3 What Kinds of Data Can Be Mined? 1.4 What Kinds of Patterns Can Be Mined? Which Technologies Are Used? Which Kinds of Applications Are Targeted? Major Issues in Data Mining. Data Objects and Attribute Types, Basic Statistical Descriptions of Data, Data Visualization, Measuring Data Similarity and Dissimilarity

### **UNIT –II**

**Data Pre-processing:** Data Preprocessing: An Overview, Data Cleaning, Data Integration, Data Reduction, Data Transformation and Data Discretization

### **UNIT –III**

**Classification:** Basic Concepts, General Approach to solving a classification problem, Decision Tree Induction: Working of Decision Tree, building a decision tree, methods for expressing an attribute test conditions, measures for selecting the best split, Algorithm for decision tree induction.

### **UNIT –IV**

**Classification: Alternative Techniques,** Bayes' Theorem, Naïve Bayesian Classification, Bayesian Belief Networks

### **UNIT –V**

**Association Analysis: Basic Concepts and Algorithms:** Problem Defecation, Frequent Item Set generation, Rule generation, compact representation of frequent item sets, FP-Growth Algorithm. **(Tan & Vipin)**

### **UNIT –VI**

**Cluster Analysis: Basic Concepts and Algorithms: Overview:** What Is Cluster Analysis? Different Types of Clustering, Different Types of Clusters; K-means: The Basic K-means Algorithm, K-means Additional Issues, Bisecting K-means, Strengths and Weaknesses; Agglomerative Hierarchical Clustering: Basic Agglomerative Hierarchical Clustering Algorithm DBSCAN: Traditional Density Center-Based Approach, DBSCAN Algorithm, Strengths and Weaknesses. **(Tan & Vipin)**

### **OUTCOMES:**

- Understand stages in building a Data Warehouse
- Understand the need and importance of preprocessing techniques
- Understand the need and importance of Similarity and dissimilarity techniques
- Analyze and evaluate performance of algorithms for Association Rules.
- Analyze Classification and Clustering algorithms

**TEXT BOOKS:**

1. Introduction to Data Mining: Pang-Ning Tan & Michael Steinbach, Vipin Kumar, Pearson.
2. Data Mining concepts and Techniques, 3/e, Jiawei Han, Michel Kamber, Elsevier.

**REFERENCE BOOKS:**

1. Data Mining Techniques and Applications: An Introduction, Hongbo Du, Cengage Learning.
2. Data Mining : Vikram Pudi and P. Radha Krishna, Oxford.
3. Data Mining and Analysis - Fundamental Concepts and Algorithms; Mohammed J. Zaki, Wagner Meira, Jr, Oxford
4. Data Warehousing Data Mining & OLAP, Alex Berson, Stephen Smith, TMH.

## **INDUSTRIAL ROBOTICS**

### **OPEN ELECTIVE**

#### **Course Objectives:**

1. To give students practice in applying their knowledge of mathematics, science, and Engineering and to expand this knowledge into the vast area of robotics.
2. The students will be exposed to the concepts of robot kinematics, Dynamics, Trajectory planning.
3. Mathematical approach to explain how the robotic arm motion can be described.
4. The students will understand the functioning of sensors and actuators.

#### **UNIT-I**

**INTRODUCTION:** Automation and Robotics, CAD/CAM and Robotics – An over view of Robotics – present and future applications – classification by coordinate system and control system.

#### **UNIT – II**

**COMPONENTS OF THE INDUSTRIAL ROBOTICS:** Function line diagram representation of robot arms, common types of arms. Components, Architecture, number of degrees of freedom – Requirements and challenges of end effectors, determination of the end effectors, comparison of Electric, Hydraulic and Pneumatic types of locomotion devices.

#### **UNIT – III**

**MOTION ANALYSIS:** Homogeneous transformations as applicable to rotation and translation – problems.

**MANIPULATOR KINEMATICS:** Specifications of matrices, D-H notation joint coordinates and world coordinates Forward and inverse kinematics – problems.

#### **UNIT – IV**

Differential transformation and manipulators, Jacobians – problems

Dynamics: Lagrange – Euler and Newton – Euler formulations – Problems.

#### **UNIT V**

General considerations in path description and generation. Trajectory planning and avoidance of obstacles, path planning, Skew motion, joint integrated motion –straight line motion – Robot programming, languages and software packages-description of paths with a robot programming language..

#### **UNIT VI**

**ROBOT ACTUATORS AND FEED BACK COMPONENTS:**

Actuators: Pneumatic, Hydraulic actuators, electric & stepper motors.

Feedback components: position sensors – potentiometers, resolvers, encoders – Velocity sensors.

**ROBOT APPLICATIONS IN MANUFACTURING:** Material Transfer - Material handling, loading and unloading- Processing - spot and continuous arc welding & spray painting - Assembly and Inspection.

**TEXT BOOKS:**

1. Industrial Robotics / Groover M P / Pearson Edu.
2. Robotics and Control / Mittal R K & Nagrath I J / TMH.

**REFERENCES:**

1. Robotics / Fu K S/ McGraw Hill.
2. Robotic Engineering / Richard D. Klafter, Prentice Hall
3. Robot Analysis and Control / H. Asada and J.J.E. Slotine / BSP Books Pvt.Ltd.
4. Introduction to Robotics / John J Craig / Pearson Edu.

**Course outcomes:**

Upon successful completion of this course you should be able to:

1. Identify various robot configuration and components,
2. Select appropriate actuators and sensors for a robot based on specific application
3. Carry out kinematic and dynamic analysis for simple serial kinematic chains
4. Perform trajectory planning for a manipulator by avoiding obstacles.

# **POWER ELECTRONICS**

## **(Open Elective)**

### **Preamble:**

The usage of power electronics in day to day life has increased in recent years. It is important for student to understand the fundamental principles behind all these converters. This course covers characteristics of semiconductor devices, ac/dc, dc/dc, ac/ac and dc/ac converters. The importance of using pulse width modulated techniques to obtain high quality power supply (dc/ac converter) is also discussed in detail in this course.

### **Learning Objectives:**

- To study the characteristics of various power semiconductor devices and to design firing circuits for SCR.
- To understand the operation of single phase half wave and full-wave converters
- To understand the operation of different types of DC-DC converters.
- To understand the operation of inverters and application of PWM techniques for voltage control and harmonic mitigation.
- To understand the operation of AC-AC converters and switch mode power supplies operation.

### **UNIT-I**

#### **Power Semi-Conductor Devices**

Thyristors–Silicon controlled rectifiers (SCR's) – Characteristics of power MOSFET and power IGBT – Basic theory of operation of SCR–Static characteristics – Turn on and turn off methods–Dynamic characteristics of SCR – Snubber circuit design – Firing circuits for SCR

### **UNIT-II**

#### **AC-DC Single-Phase Converters**

Single phase half wave controlled rectifiers – R load and RL load with and without freewheeling diode – Single Phase full wave controlled rectifiers – center tapped configuration and bridge configuration – R load and RL load with and without freewheeling diode – Effect of source inductance in 1-phase fully controlled bridge rectifier.

### **UNIT-III**

#### **DC-DC Converters**

Buck Converter operation – Time ratio control and current limit control strategies–Voltage and current waveforms– Derivation of output voltage –Boost converter operation –Voltage and current waveforms–Derivation of output voltage – Buck-Boost converter operation –Voltage and current waveforms – Principle operation of forward and fly back converters

### **UNIT – IV**

#### **DC-AC Converters**

Single phase inverters–Unipolar and bipolar switching – Single phase half bridge and full bridge inverters with R and RL loads – PWM techniques– Sine triangular PWM technique– amplitude and frequency modulation Indices – Harmonic analysis.

### **UNIT – V**

#### **AC – AC Single-Phase Converters**

Static V-I characteristics of TRIAC and modes of operation – Single phase AC-AC regulator phase angle control and integrated cycle control with R and RL load – For continuous and discontinuous conduction – Principle of operation of Cyclo-Converters

### **UNIT – VI**

#### **Switch Mode Power Supplies**

Overview of Switching Power Supplies – Linear Power Supplies – DC to DC converters with electrical isolation – Control of Switch Mode DC Supplies – PWM duty ratio control – Current mode control – Power Supply Protection

**Learning Outcomes:**

Student should be able to

- Explain the characteristics of various power semiconductor devices and analyse the static and dynamic characteristics of SCR's.
- Design firing circuits for SCR.
- Able to explain the operation of single phase half wave and full-wave converters
- Analyse the operation of different types of DC-DC converters.
- Explain the operation of inverters and application of PWM techniques for voltage control and harmonic mitigation.
- Analyse the operation of AC-AC converters.
- Able to explain switch mode power supplies operation and control

**Text Books:**

1. Power Electronics: Circuits, Devices and Applications – by M. H. Rashid, Prentice Hall of India, 2nd edition, 1998
2. Power Electronics: Essentials & Applications by L.Umanand, Wiley, Pvt. Limited, India, 2009

**Reference Books:**

1. Power Electronics: converters, applications & design -by Nedmohan, Tore M. Undeland, Robbins by Wiley India Pvt. Ltd.
2. Elements of Power Electronics–Philip T.Krein.oxford.
3. Power Electronics – by P.S.Bhimbra, Khanna Publishers.
4. Power Electronics handbook by Muhammad H.Rashid, Elsevier.
5. Power Converter Circuits -by William Shepherd, Li zhang, CRC Taylor & Francis Group.

**BIO-MEDICAL ENGINEERING  
(OPEN ELECTIVE)**

**UNIT-I:**

**INTRODUCTION TO BIOMEDICAL INSTRUMENTATION:** Age of Biomedical Engineering, Development of Biomedical Instrumentation, Man Instrumentation System, Components of the Man-Instrument System, Physiological System of the Body, Problems Encountered in Measuring a Living System, Sources of Bioelectric Potentials, Muscle, Bioelectric Potentials, Sources of Bioelectric Potentials, Resting and Action Potentials, Propagation of Action Potential, Bioelectric Potentials-ECG, EEG and EMG, Evoked Responses.

**UNIT-II:**

**ELECTRODES AND TRANSDUCERS:** Introduction, Electrode Theory, Biopotential Electrodes, Examples of Electrodes, Basic Transducer Principles, Biochemical Transducers, The Transducer and Transduction Principles, Active Transducers, Passive Transducers, Transducers for Biomedical Applications, Pulse Sensors, Respiration Sensor, Transducers with Digital Output.

**UNIT-III:**

**CARDIOVASCULAR SYSTEM AND MEASUREMENTS:** The Heart and Cardiovascular System, Electro Cardiography, Blood Pressure Measurement, Measurement of Blood Flow and Cardiac Output, Measurement of Heart Sound, Plethysmography.

**MEASUREMENTS IN THE RESPIRATORY SYSTEM:** The Physiology of The Respiratory System, Tests and Instrumentation for The Mechanics of Breathing, Respiratory Therapy Equipment.

**UNIT-IV:**

**PATIENT CARE AND MONITORING:** Elements of Intensive-Care Monitoring, Patient Monitoring Displays, Diagnosis, Calibration and Repair ability of Patient-Monitoring Equipment, Other Instrumentation for Monitoring Patients, Organization of the Hospital for Patient-Care Monitoring, Pacemakers, Defibrillators, Radio Frequency Applications of Therapeutic use.

**THERAPEUTIC AND PROSTHETIC DEVICES:** Audiometers and Hearing Aids, Myoelectric Arm, Laparoscope, Ophthalmology Instruments, Anatomy of Vision, Electrophysiological Tests, Ophthalmoscope, Tonometer for Eye Pressure Measurement, Diathermy, Clinical Laboratory Instruments, Biomaterials, Stimulators.

**UNIT-V:**

**DIAGNOSTIC TECHNIQUES AND BIO-TELEMETRY:** Principles of Ultrasonic Measurement, Ultrasonic Imaging, Ultrasonic Applications of Therapeutic Uses, Ultrasonic Diagnosis, X-Ray and Radio-Isotope Instrumentations, CAT Scan, Emission Computerized Tomography, MRI, Introduction to Biotelemetry, Physiological Parameters Adaptable to Biotelemetry, The Components of Biotelemetry System, Implantable Units, Telemetry for ECG Measurements during Exercise, Telemetry for Emergency Patient Monitoring



**UNIT-VI:**

**MONITORS, RECORDERS AND SHOCK HAZARDS:** Biopotential Amplifiers, Monitors, Recorders, Shock Hazards and Prevention, Physiological Effects and Electrical Current, Shock Hazards from Electrical Equipment, Methods of Accident Prevention, Isolated Power Distribution System.

**Text Books:**

1. “Bio-Medical Electronics and Instrumentation”, Onkar N. Pandey, Rakesh Kumar, Katson Books.
2. “Bio-Medical Instrumentation”, Cromewell , Wiebell, Pfeiffer

**References:**

1. “Introduction to Bio-Medical Equipment Technology”, 4<sup>th</sup> Edition, Joseph J. Carr, John M. Brown, Pearson Publications.
2. “Hand Book of Bio-Medical Instrumentation”, Khandapur. McGrawHill

# ARTIFICIAL NEURAL NETWORKS

## OPEN ELECTIVE

### Course Objectives:

1. To Introduce the concept of Artificial Neural Networks , Characteristics, Models of Neuron, Learning Rules, Learning Methods, Stability and Convergence
2. To study the basics of Pattern Recognition and Feed forward Neural Networks
3. To study the basics of Feedback neural networks and Boltzmann machine
4. To introduce the Analysis of Feedback layer for different output functions, Pattern Clustering and Mapping networks
5. To study the Stability, Plasticity, Neocognitron and Different applications of Neural Networks

### UNIT-I : Basics of Artificial Neural Networks

Introduction: Biological Neural Networks, Characteristics of Neural Networks, Models of Neuron, Topology, Basic Learning Rules

Activation and Synaptic Dynamics: Activation Dynamic Models, Synaptic Dynamic Models, Learning Methods, Stability & Convergence, Recall in Neural Networks

**UNIT-II:** Functional Units of ANN for Pattern Recognition Tasks: Pattern Recognition problem Basic Fundamental Units, Pattern Recognition Tasks by the Functional Units

Feed forward Neural Networks: Analysis of Pattern Association Networks, Analysis of Pattern Classification Networks, Analysis of Pattern Mapping Networks

### UNIT-III:

Feedback Neural Networks: Analysis of linear auto adaptive feed forward networks, Analysis of pattern storage Networks, Stochastic Networks & Stimulated Annealing, Boltzmann machine

### UNIT-IV:

Competitive Learning Neural Networks: Components of a Competitive Learning Network, Analysis of Feedback layer for Different Output Functions, Analysis of Pattern Clustering Networks and Analysis of Feature Mapping Network

### UNIT-V:

Architectures for Complex Pattern Recognition Tasks: Associative memory, Pattern mapping Stability – Plasticity dilemma: ART, temporal patterns, Pattern visibility: Neocognitron

### UNIT-VI:

Applications of Neural Networks: Pattern classification, Associative memories, Optimization, Applications in Image Processing, Applications in decision making

**Text Book**

1. B.Yagnanarayana“Artificial Neural Networks”, PHI

**Reference Book**

1. Laurene Fausett ,“Fundamentals of Neural Networks”, Pearson Education
2. Simon Haykin , “Neural Networks”, Second Edition

**Course Outcomes**

1. This Course introduces Artificial Neural Networks and Learning Rules and Learning methods
2. Feed forward and Feedback Neural Networks are introduced
3. Applications of Neural Networks in different areas are introduced

III Year - II Semester

L	T	P	C
0	0	3	2

## MICROPROCESSORS AND MICROCONTROLLERS LAB

### LIST OF EXPERIMENTS

#### **PART- A: (Minimum of 5 Experiments has to be performed)**

##### **8086 Assembly Language Programming using Assembler Directives**

15. Sorting.
16. Multibyte addition/subtraction
17. Sum of squares/cubes of a given n-numbers
18. Addition of n-BCD numbers
19. Factorial of given n-numbers
20. Multiplication and Division operations
21. Stack operations
22. BCD to Seven segment display codes

#### **PART- B: (Minimum of 3 Experiments has to be performed)**

##### **8086 Interfacing**

1. Hardware/Software Interrupt Application
2. A/D Interface through Intel 8255
3. D/A Interface through Intel 8255
4. Keyboard and Display Interface through Intel 8279
5. Generation of waveforms using Intel 8253/8254

#### **PART- C: (Minimum of 3 Experiments has to be performed)**

##### **8051 Assembly Language Programs**

1. Finding number of 1's and number of 0's in a given 8-bit number
2. Addition of even numbers from a given array
3. Ascending / Descending order
4. Average of n-numbers

#### **PART-D: (Minimum of 3 Experiments has to be performed)**

##### **8051 Interfacing**

1. Switches and LEDs
2. 7-Segment display (multiplexed)
3. Stepper Motor Interface
4. Traffic Light Controller

**Equipment Required:**

1. Regulated Power supplies
2. Analog/Digital Storage Oscilloscopes
3. 8086 Microprocessor kits
4. 8051 microcontroller kits
5. ADC module
6. DAC module
7. Stepper motor module
8. Keyboard module
9. LED, 7-Segment Units
10. Digital Multimeters
11. ROM/RAM Interface module
12. Bread Board etc.

**III Year - II Semester**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>0</b>	<b>0</b>	<b>3</b>	<b>2</b>

**VLSI LABORATORY**

**Note:** The students are required to design the schematic diagrams using CMOS logic and to draw the layout diagrams to perform the following experiments using 130nm technology with the Industry standard EDA Tools.

**List of Experiments:**

- i. Design and Implementation of an Universal Gates
- ii. Design and Implementation of an Inverter
- iii. Design and Implementation of Full Adder
- iv. Design and Implementation of Full Subtractor
- v. Design and Implementation of Decoder
- vi. Design and Implementation of RS-Latch
- vii. Design and Implementation of D-Latch
- viii. Design and Implementation asynchronous counter
- ix. Design and Implementation of static RAM cell
- x. Design and Implementation of 8 bit DAC using R-2R ladder network

**Software Required:**

- i. Mentor Graphics Software / Equivalent Industry Standard Software.
- ii. Personal computer system with necessary software to run the programs and to implement.

**III Year - II Semester**

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>0</b>	<b>0</b>	<b>3</b>	<b>2</b>

**DIGITAL COMMUNICATIONS LAB**

1. Time division multiplexing.
2. Pulse code modulation.
3. Differential pulse code modulation.
4. Delta modulation.
5. Frequency shift keying.
6. Phase shift keying .
7. Differential phase shift keying.
8. Companding
9. Source Encoder and Decoder
10. Linear Block Code-Encoder and Decoder
11. Binary Cyclic Code – Encoder and Decoder
12. Convolution Code – Encoder and Decoder

**Equipment required for Laboratories:**

1. RPS – 0 – 30 V
2. CRO – 0 – 20 M Hz.
3. Function Generators – 0 – 1 M Hz
4. RF Generators – 0 – 1000 M Hz./0 – 100 M Hz.
5. Multimeters
6. Lab Experimental kits for Digital Communication
7. Components

III Year - II Semester

<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
<b>0</b>	<b>2</b>	<b>0</b>	<b>0</b>

## INTELLECTUAL PROPERTY RIGHTS AND PATENTS

### UNIT I: Introduction to Intellectual Property Rights (IPR)

Concept of Property - Introduction to IPR – International Instruments and IPR - WIPO - TRIPS – WTO -Laws Relating to IPR - IPR Tool Kit - Protection and Regulation - Copyrights and Neighboring Rights – Industrial Property – Patents - Agencies for IPR Registration – Traditional Knowledge –Emerging Areas of IPR - Layout Designs and Integrated Circuits – Use and Misuse of Intellectual Property Rights.

### UNIT II: Copyrights and Neighboring Rights

Introduction to Copyrights – Principles of Copyright Protection – Law Relating to Copyrights - Subject Matters of Copyright – Copyright Ownership – Transfer and Duration – Right to Prepare Derivative Works –Rights of Distribution – Rights of Performers – Copyright Registration – Limitations – Infringement of Copyright – Relief and Remedy – Case Law - Semiconductor Chip Protection Act.

### UNIT III: Patents

Introduction to Patents - Laws Relating to Patents in India – Patent Requirements – Product Patent and Process Patent - Patent Search - Patent Registration and Granting of Patent - Exclusive Rights – Limitations - Ownership and Transfer — Revocation of Patent – Patent Appellate Board - Infringement of Patent – Double Patenting — Patent Cooperation Treaty – New developments in Patents – Software Protection and Computer related Innovations.

### UNIT IV: Trademarks

Introduction to Trademarks – Laws Relating to Trademarks – Functions of Trademark – Distinction between Trademark and Property Mark – Marks Covered under Trademark Law - Trade Mark Registration – Trade Mark Maintenance – Transfer of rights - Deceptive Similarities - Likelihood of Confusion - Dilution of Ownership – Trademarks Claims and Infringement – Remedies – Passing Off Action.

### UNIT V: Trade Secrets

Introduction to Trade Secrets – General Principles - Laws Relating to Trade Secrets - Maintaining Trade Secret – Physical Security – Employee Access Limitation – Employee Confidentiality Agreements – Breach of Contract – Law of Unfair Competition – Trade Secret Litigation – Applying State Law.

### UNIT VI: Cyber Law and Cyber Crime

Introduction to Cyber Law – Information Technology Act 2000 - Protection of Online and Computer Transactions - E-commerce - Data Security – Authentication and Confidentiality - Privacy - Digital Signatures – Certifying Authorities - Cyber Crimes - Prevention and Punishment – Liability of Network Providers.

- Relevant Cases Shall be dealt where ever necessary.



**References:**

1. Intellectual Property Rights (Patents & Cyber Law), Dr. A. Srinivas. Oxford University Press, New Delhi.
2. Deborah E. Bouchoux: Intellectual Property, Cengage Learning, New Delhi.
3. PrabhuddhaGanguli: Intellectual Property Rights, Tata Mc-Graw –Hill, New Delhi
4. Richard Stim: Intellectual Property, Cengage Learning, New Delhi.
5. Kompal Bansal & Parishit Bansal Fundamentals of IPR for Engineers, B. S. Publications (Press).
6. Cyber Law - Texts & Cases, South-Western's Special Topics Collections.
7. R.Radha Krishnan, S.Balasubramanian: Intellectual Property Rights, Excel Books. New Delhi.
8. M.Ashok Kumar and MohdIqbal Ali: Intellectual Property Rights, Serials Pub.